

Introduction to MHD dynamos

A photograph of a cross-section of a tree trunk, showing concentric growth rings. The rings are a reddish-brown color, and the wood is a lighter tan. The image is used as a metaphor for dynamo theory, where the growth rings represent the complex, swirling patterns of magnetic field lines in a dynamo.

François Rincon

Bed time reading:

Dynamo theories
J. Plasma Phys. (Lecture Notes Series) 85, 205850401 (2019)
arXiv:1903.07829

Tutorial outline

- Context
 - Short and easy (3h)
- Setting the theory stage
 - Not too long and straightforward (4h)
- Small scale MHD dynamos
 - Long and difficult (6h)
- Large-scale MHD dynamos
 - Just a tad shorter, a bit less difficult (4h)
- Connections between large & small-scale dynamos
 - Short and controversial, also difficult (2h)
- Instability-driven MHD dynamos
 - Short and seemingly easier, but actually differently difficult (3h)
- Collisionless plasma dynamo
 - Short and a bit crazy, and even more difficult (4h)

Today

Second session
(February, or whenever you want)

What is dynamo theory about ?

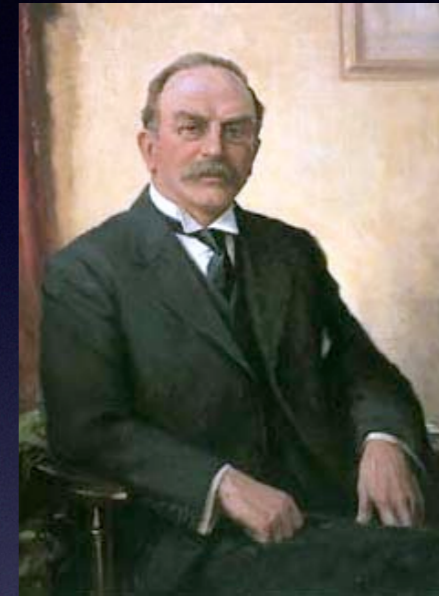
- The **origin, and sustainment, of magnetic fields** in the universe
 - on the Earth, other planets and their satellites (“**planetary magnetism**”)
 - in the Sun and other stars (“**stellar magnetism**”)
 - in galaxies, clusters and the early universe (“**cosmic magnetism**”)
- Understanding their **structural, statistical, and dynamical** properties
- **Addressing important physics (and maths) problems**
 - Deep **connections** with **hydrodynamic turbulence** and more generally **(turbulent) transport** problems
- Coming up with “**useful stuff**” for **experimentalists** and **observers**
 - **Warning:** people strongly disagree on the definition of “useful stuff”

The fluid/plasma dynamo conundrum

- Most astrophysical bodies, and many planetary interiors, are
 - in an electrically conducting fluid (MHD) or weakly-collisional plasma state
 - in a turbulent state
 - (differentially) rotating: shearing, Coriolis and precessing effects
- Main questions
 - Can flows of electrically conducting fluid/plasma amplify magnetic fields ?
 - What are the time and spatial scales on which this happens ?
 - At what amplitude do they saturate ? What field structure is produced ?
- A complex and multifaceted problem
 - Requires observations, phenomenology, theory, numerics and experiments

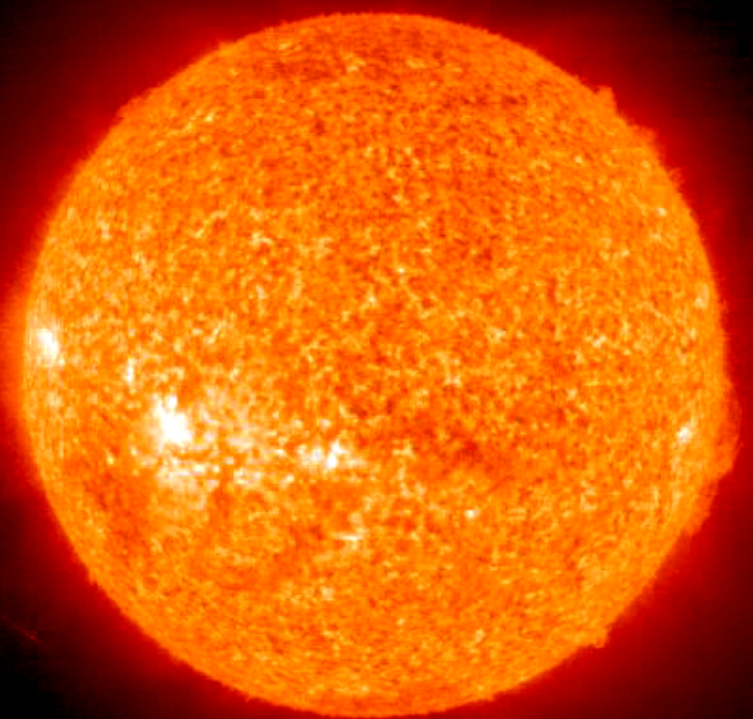
A touch of history

- Self-exciting **fluid dynamos** are now a century-old idea
 - First invoked by **Larmor** in **1919** (sunspot magnetism)
- The idea took a lot of time to gain ground
 - **Cowling's** antidynamo theorem (**1933**)
 - First examples in the **1950s** (e.g. **Herzenberg** dynamo)
 - **Parker's** solar dynamo phenomenology (**1955**)
- Golden age of **mathematical theory**
 - **Alpha effect / mean-field**: Steenbeck, Krause, Raedler **1966**, Moffatt, Roberts etc. (1970s)
 - **Small-scale** dynamo theory: Kazantsev **1967**, Kraichnan, Zel'dovich et al. (70s-80s)
- **Numerical** and **experimental** era
 - **Numerical** evidence of turbulent dynamos: Meneguzzi et al. **1981**, flourishing since then
 - **Experimental** evidence: Riga, Karlsruhe (~**2000**), VKS (2007), plasma underway (2005+)
 - Great **observational** radio and spectro-polarimetric **prospects** too (stellar, galactic, cosmo)

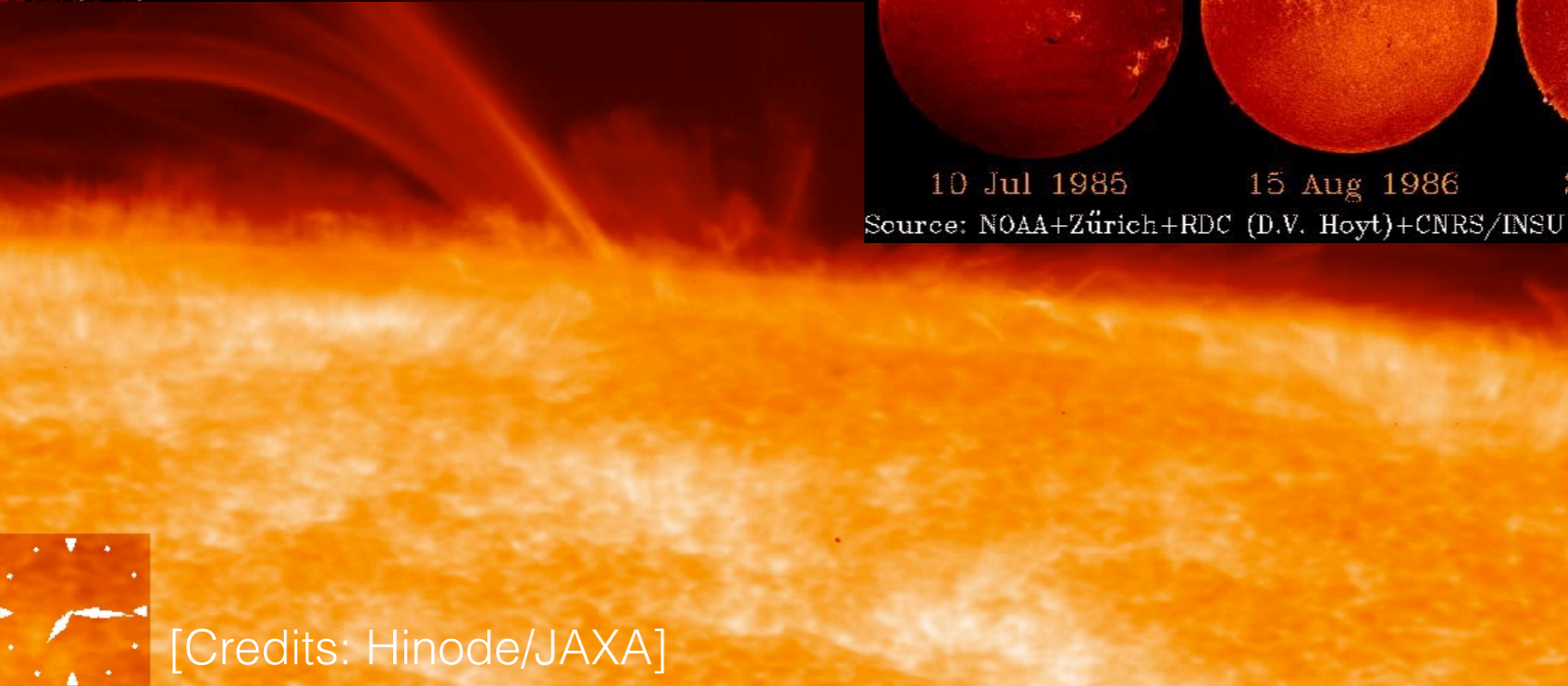


Solar magnetism

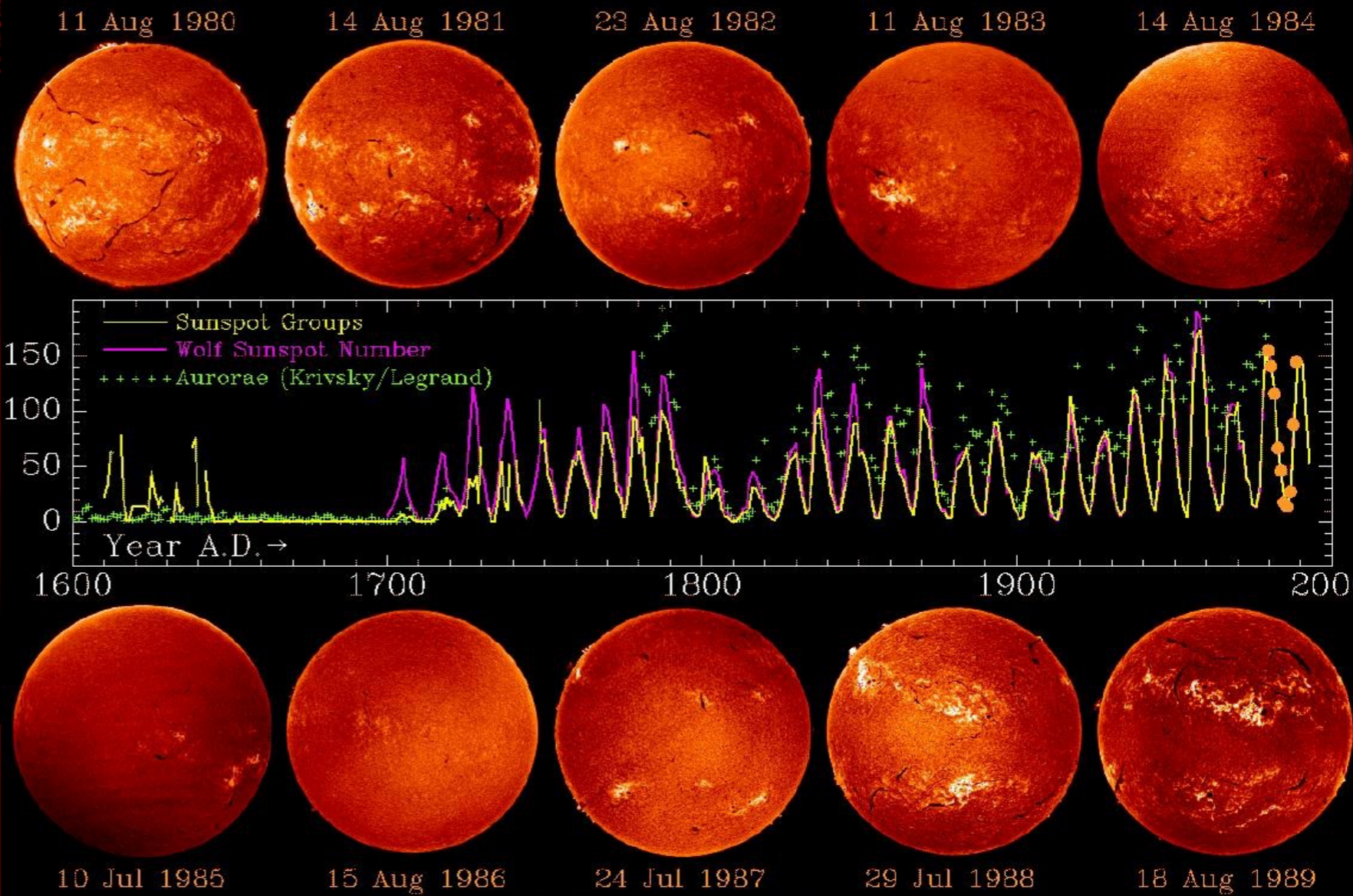
[Credits: SOHO/NASA]



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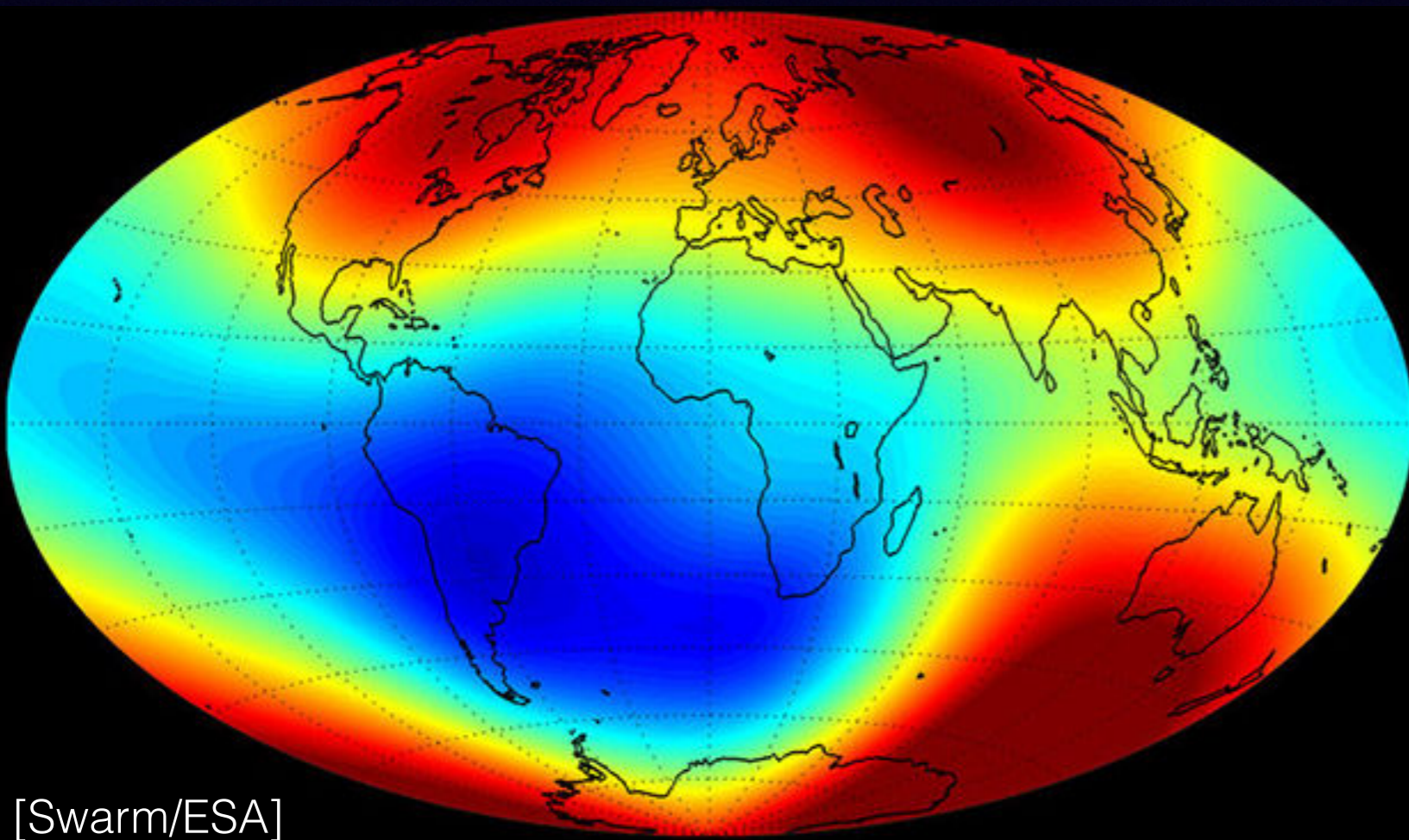
[Credits: Hinode/JAXA]



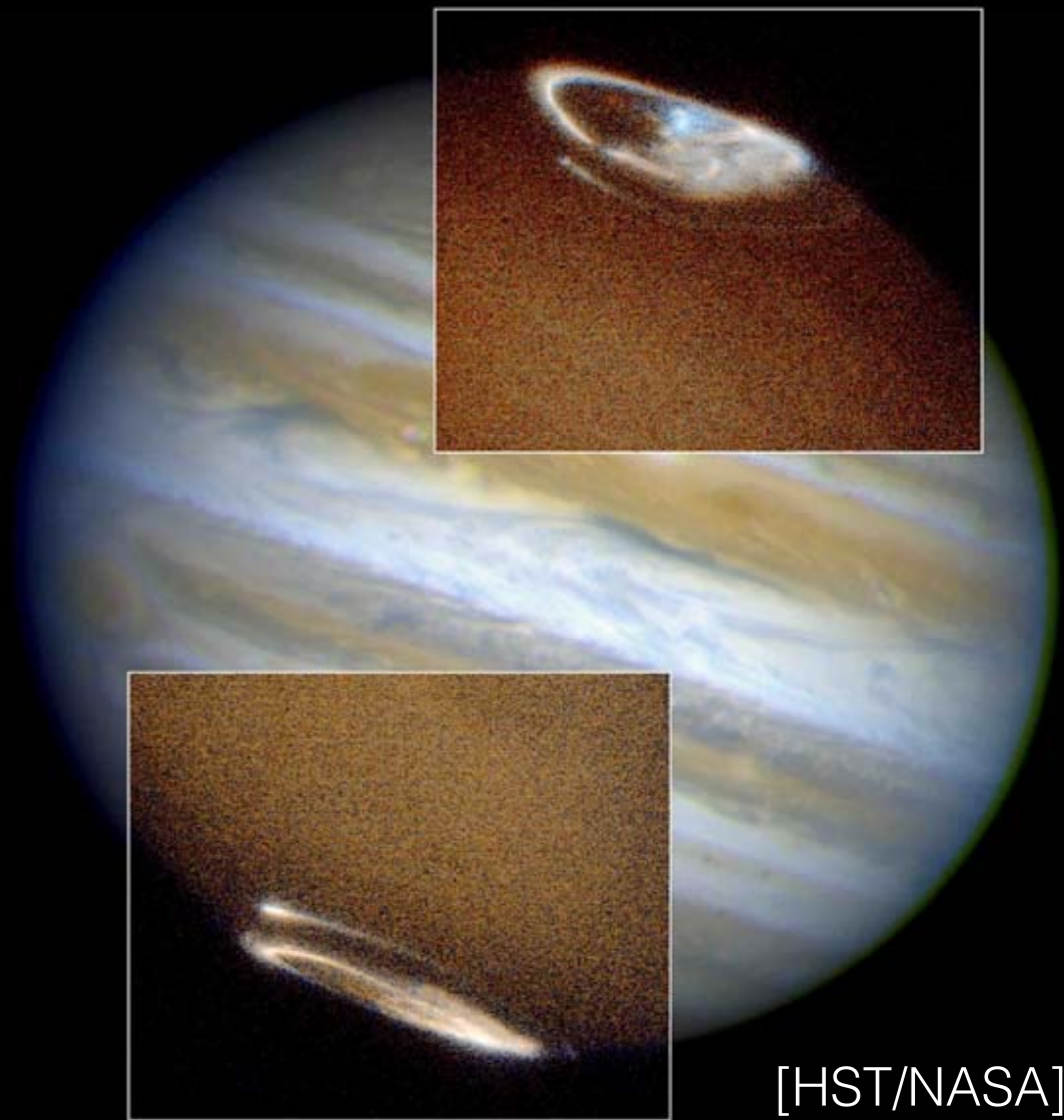
Source: NOAA+Zürich+RDC (D.V. Hoyt)+CNRS/INSU (J.-P. Legrand)+Ondrejov Obs. (K. Krivsky) HAO A-017

Global solar cycle dynamics
~ 1G-a few kG (sunspots)
Small-scale surface dynamics
~ up to kG

Planetary magnetism



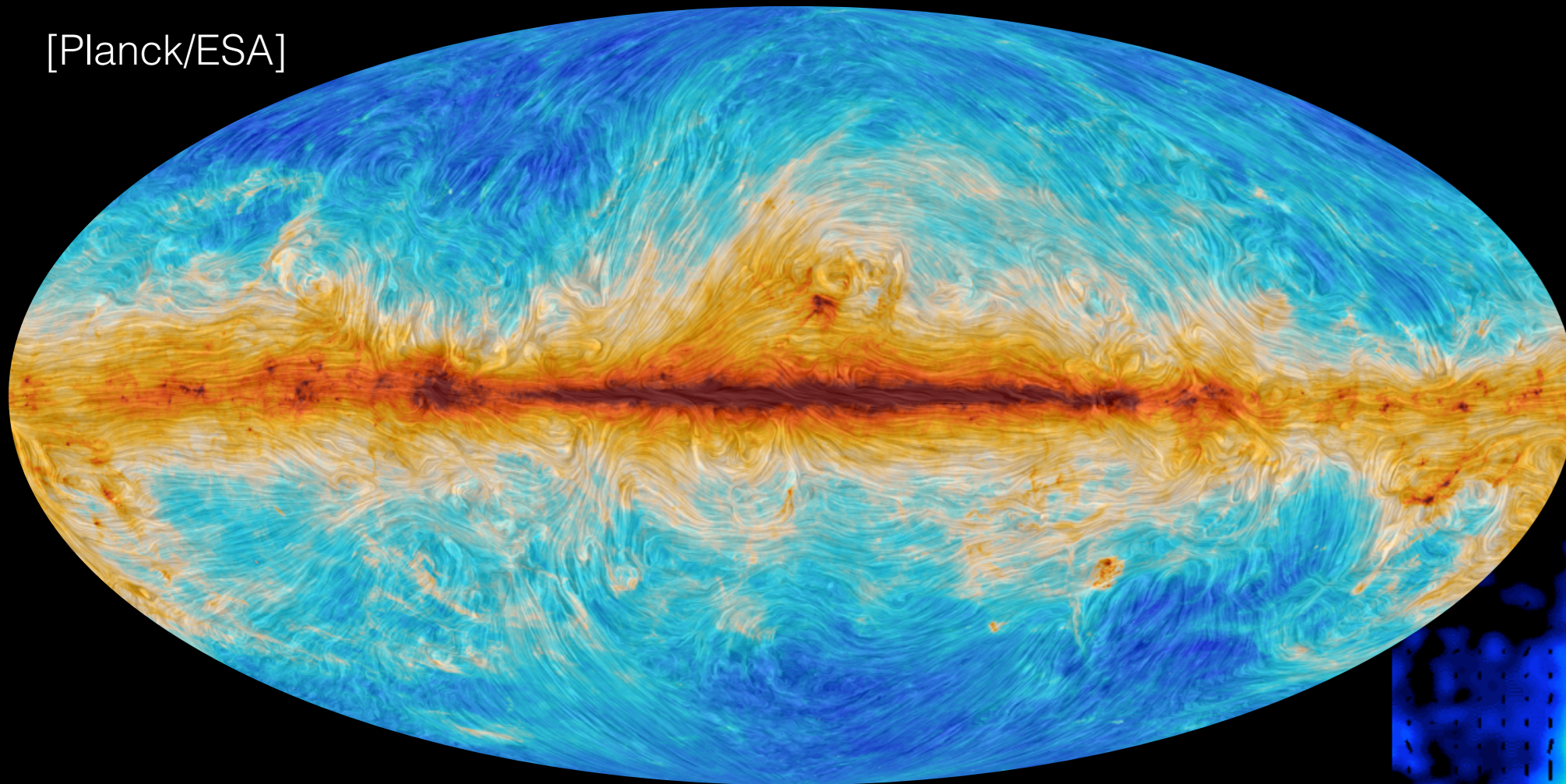
Earth's magnetic field (2014) ~ 10-50 G
(0.1-0.5 G at the surface)



Jupiter Auroras

Galactic magnetism

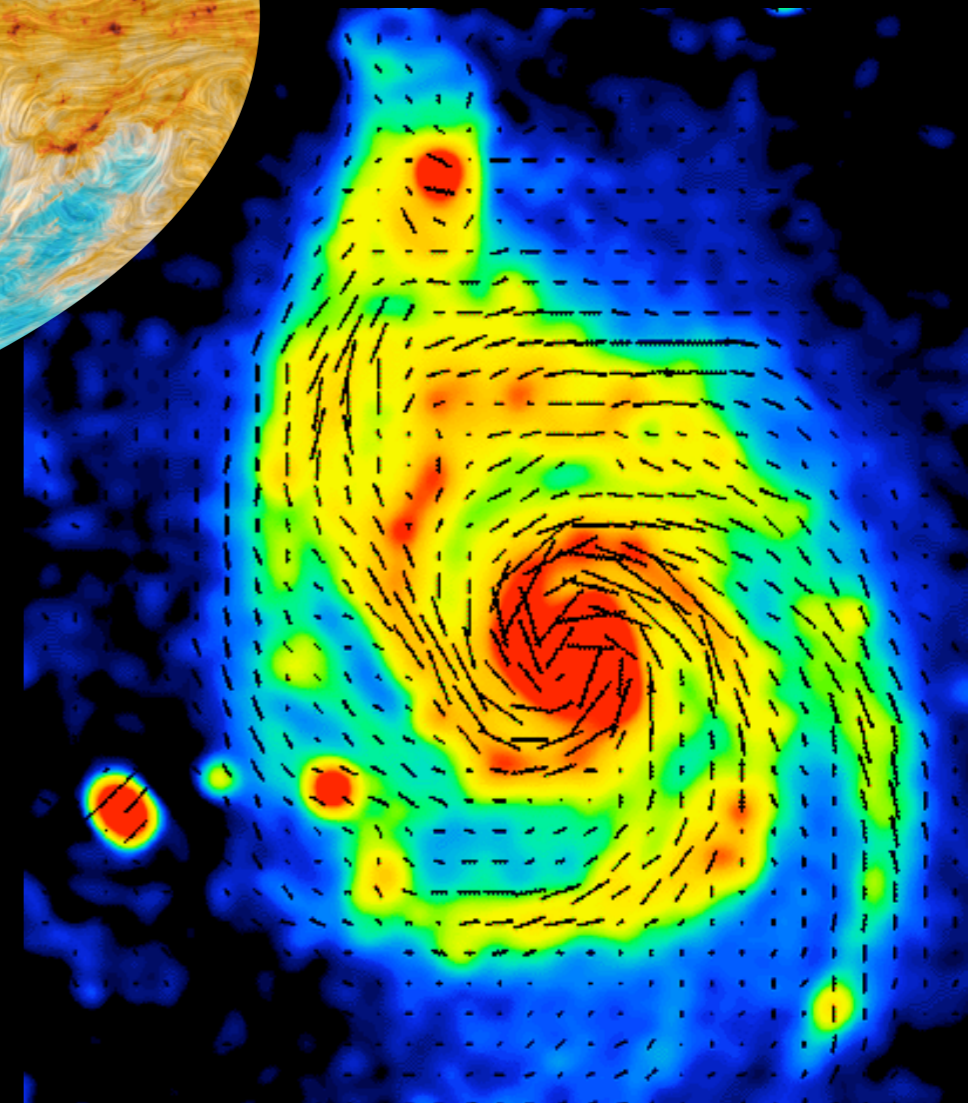
[Planck/ESA]



Galactic magnetic field $\sim 10 \mu\text{G}$

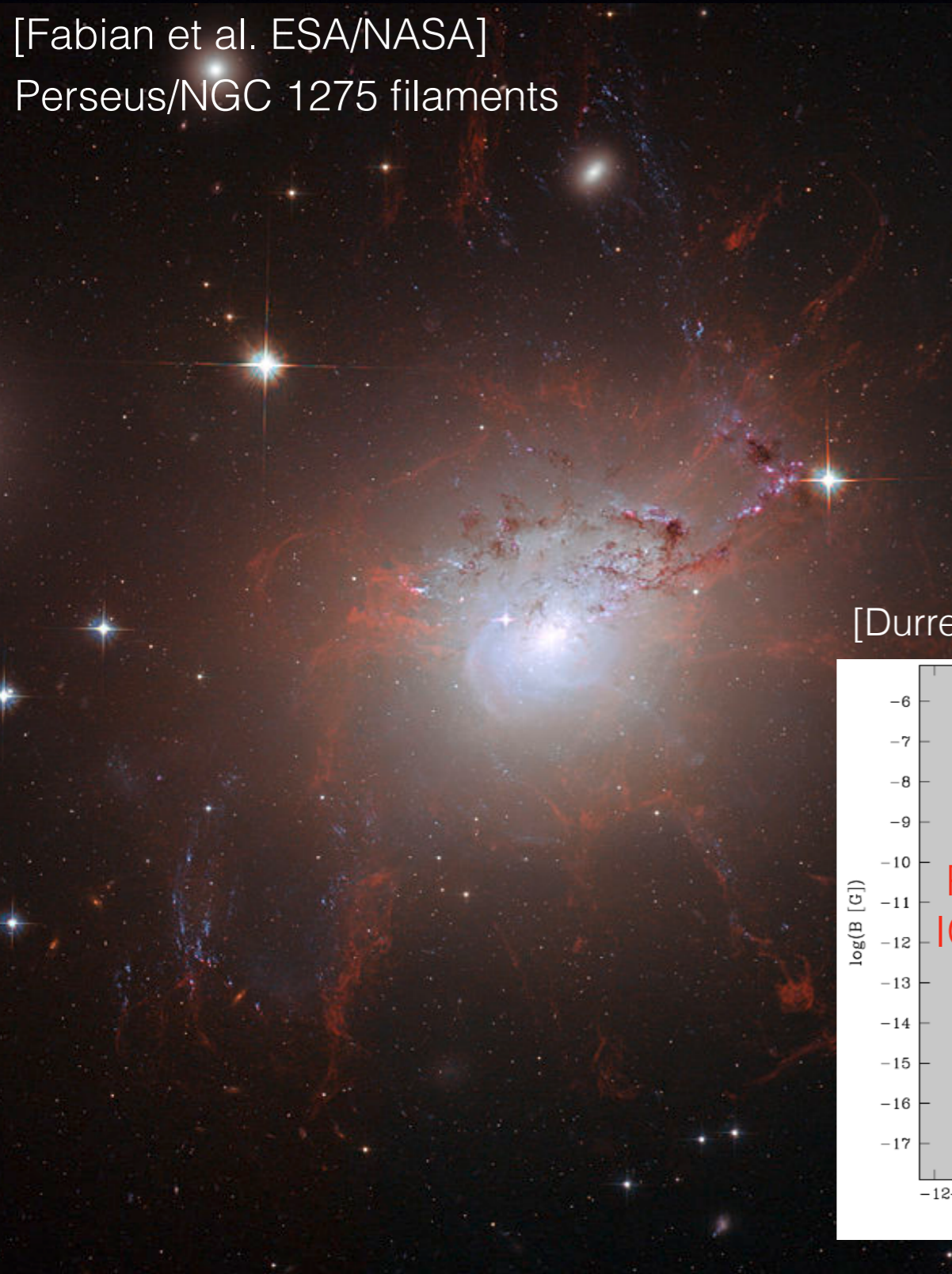
M51 magnetic field

[Beck et al. VLA/Effelsberg]



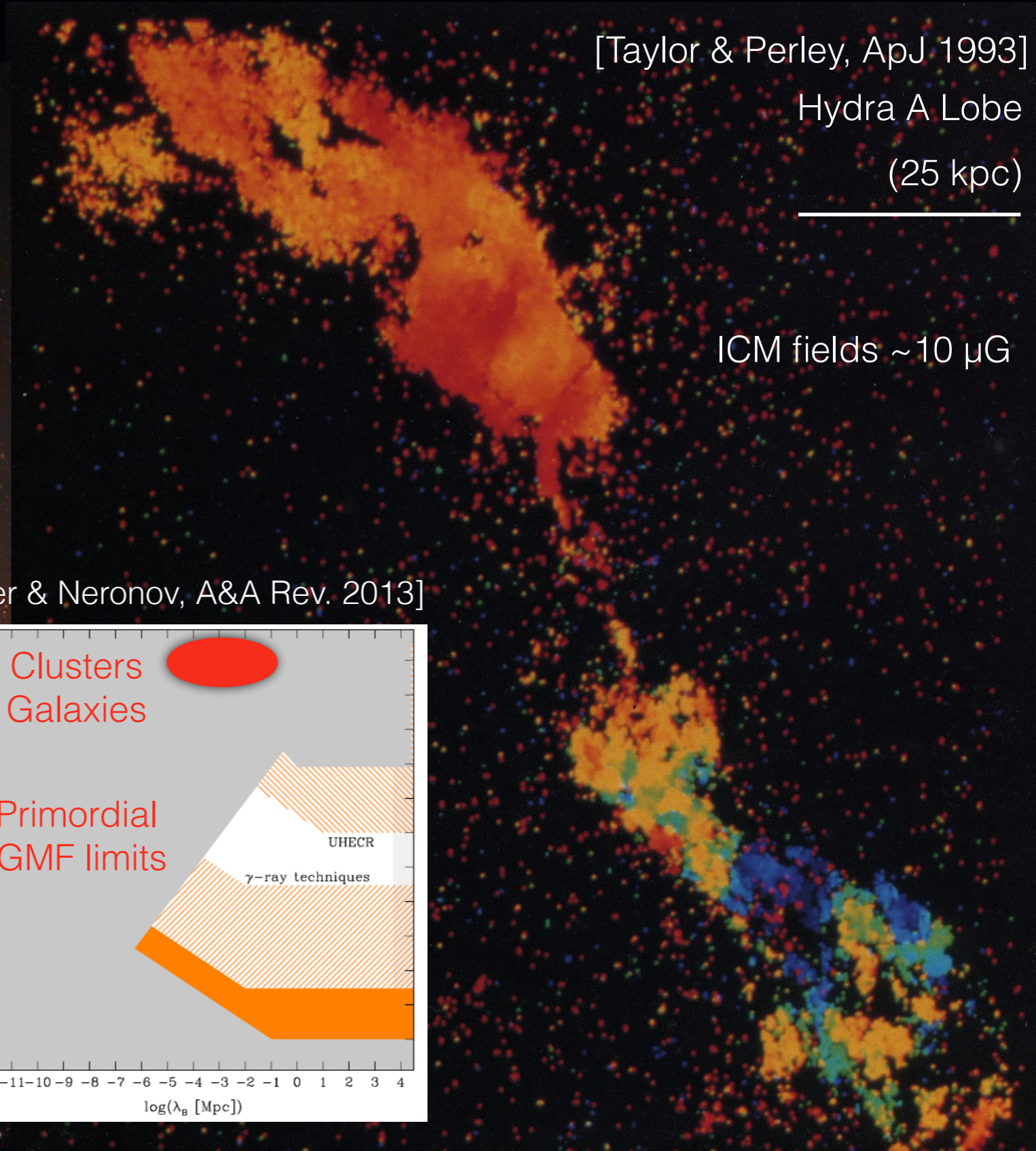
Galaxy clusters and cosmic magnetism

[Fabian et al. ESA/NASA]
Perseus/NGC 1275 filaments



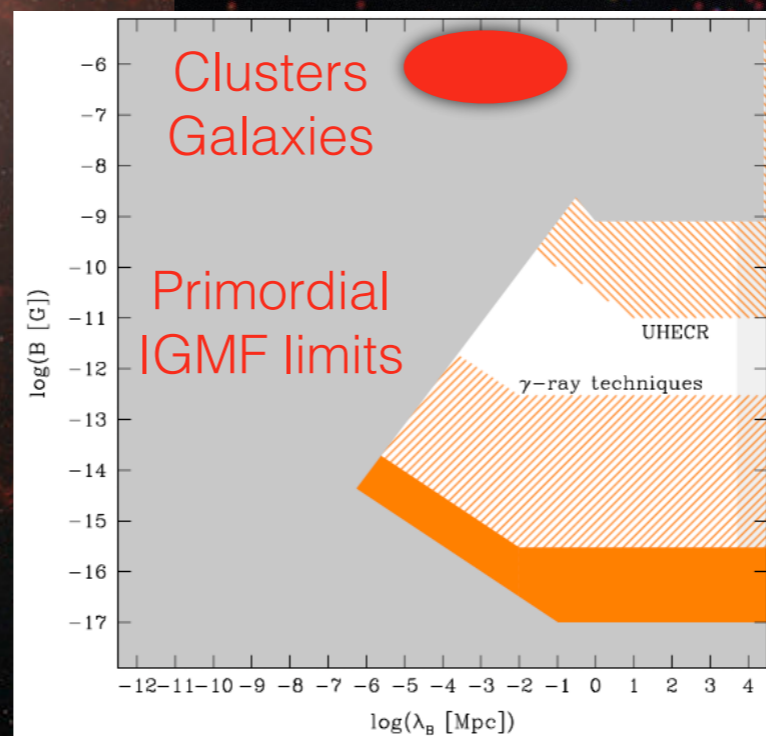
[Taylor & Perley, ApJ 1993]

Hydra A Lobe
(25 kpc)



ICM fields $\sim 10 \mu\text{G}$

[Durrer & Neronov, A&A Rev. 2013]



Takeaway phenomenological points

- Many astrophysical objects have **global, ordered fields**
 - **Differential rotation, global symmetries and geometry** important
 - **Coherent structures and MHD instabilities** may also be very important
 - Motivation for the development of “**large-scale**” **dynamo theories**
- Lots of “**small-scale**”, **random fields** also discovered from the 70s
 - These come **hand in hand** with **global magnetism**
 - Simultaneous development of “**small-scale dynamo**” **theory**
- Astrophysical magnetism is in a **nonlinear, saturated state**
 - **Linear** theory likely **not the whole story** (or requires non-trivial justification)
 - **Multiple scale interactions** expected to be important

Setting the stage

Mathematical formulation

- Compressible, viscous, resistive MHD equations

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0$$

$$\rho \left(\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right) = -\nabla p + \frac{\mathbf{j} \times \mathbf{B}}{c} + \nabla \cdot \boldsymbol{\tau} + \mathbf{F}(\mathbf{x}, t)$$

Lorentz force
External forcing (spoon, gravity etc.)

Viscous stresses

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{u} \times \mathbf{B}) - \nabla \times (\eta \nabla \times \mathbf{B})$$

Electromotive force
Magnetic diffusion $\eta = \frac{c^2}{4\pi\sigma}$

$$\tau_{ij} = \mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} - \frac{2}{3} \delta_{ij} \nabla \cdot \mathbf{u} \right)$$

$$\nabla \cdot \mathbf{B} = 0 \quad \mathbf{j} = \frac{c}{4\pi} \nabla \times \mathbf{B}$$

$$\rho T \left(\frac{\partial s}{\partial t} + \mathbf{u} \cdot \nabla s \right) = D_\mu + D_\eta + \nabla \cdot (\kappa \nabla T)$$

Dissipation
Thermal diffusion

Magnetic field energetics

- Magnetic energy equation

$$\frac{d}{dt} \int \frac{\mathbf{B}^2}{8\pi} dV = - \int \mathbf{u} \cdot \frac{(\mathbf{j} \times \mathbf{B})}{c} dV - \frac{c}{4\pi} \oint (\mathbf{E} \times \mathbf{B}) \cdot d\mathbf{S} - \int \frac{\mathbf{j}^2}{\sigma} dV$$

Minus the work of the
Lorentz force on the flow

Poynting flux

Ohmic dissipation

- Magnetic field is generated at the expense of kinetic energy
- Simple but enlightening local equation (ideal MHD)

$$\frac{1}{B} \frac{DB}{Dt} = \hat{\mathbf{b}} \hat{\mathbf{b}} : \nabla \mathbf{u} - \nabla \cdot \mathbf{u}$$

Stretching
rate

Compression
rate

$$\hat{\mathbf{b}} = \frac{\mathbf{B}}{B}$$

$$\frac{D}{Dt} = \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla$$

Conservation laws in ideal MHD

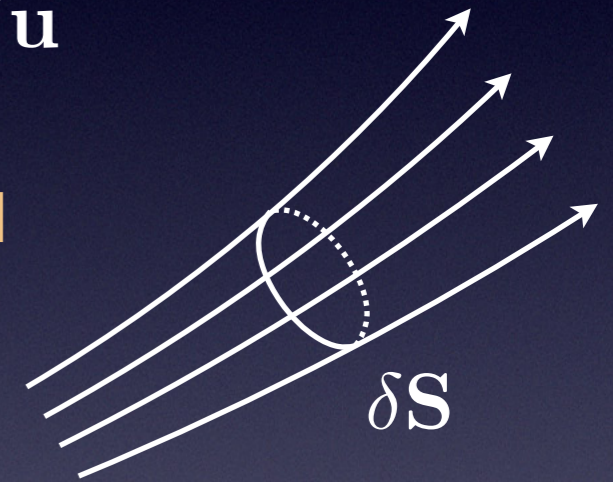
- Alfvén's theorem(s)

- Magnetic field lines are “frozen into” the fluid just as material lines

$$\frac{D}{Dt} \left(\frac{\mathbf{B}}{\rho} \right) = \frac{\mathbf{B}}{\rho} \cdot \nabla \mathbf{u} \quad \frac{D\delta\mathbf{r}}{Dt} = \delta\mathbf{r} \cdot \nabla \mathbf{u}$$

- Magnetic flux through material surfaces is conserved

$$\frac{D}{Dt} (\mathbf{B} \cdot \delta\mathbf{S}) = 0$$

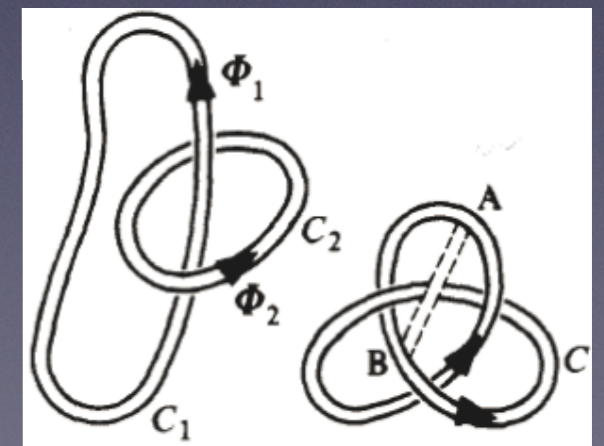


- Magnetic helicity $\mathcal{H}_m = \int \mathbf{A} \cdot \mathbf{B} d^3\mathbf{r}$ conservation

- A measure of magnetic linkage / knottedness

$$\frac{1}{c} \frac{\partial \mathbf{A}}{\partial t} = -\mathbf{E} - \nabla\varphi$$

$$\frac{\partial}{\partial t} (\mathbf{A} \cdot \mathbf{B}) + \nabla \cdot [c\varphi\mathbf{B} + \mathbf{A} \times (\mathbf{u} \times \mathbf{B})] = 0$$



Simple MHD system for dynamo theory

- Incompressible, resistive, viscous MHD
 - Captures a great deal of the dynamo problem

$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = -\nabla P + \mathbf{B} \cdot \nabla \mathbf{B} + \nu \Delta \mathbf{u} + \mathbf{f}(\mathbf{x}, t)$$

Magnetic tension

$$\frac{\partial \mathbf{B}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{B} = \mathbf{B} \cdot \nabla \mathbf{u} + \eta \Delta \mathbf{B}$$

Induction/stretching Resistive diffusion

$P = p + \frac{B^2}{2}$

Advection

$$\nabla \cdot \mathbf{u} = 0 \quad \nabla \cdot \mathbf{B} = 0 \quad p \text{ and } \mathbf{B} \text{ rescaled by } \rho \text{ and } (4\pi\rho)^{1/2}$$

- Often paired with simple periodic boundary conditions
 - Can be problematic in some cases (more later)

Scales and dimensionless numbers

- System/integral scale ℓ_0, U_0
- Fluid system with two dissipation channels

- Dimensionless numbers:

$$\text{Re} = \frac{\ell_0 U_0}{\nu} \quad \text{Rm} = \frac{\ell_0 U_0}{\eta} \quad \text{Pm} = \frac{\nu}{\eta}$$

- Kolmogorov viscous scale $\ell_v \sim \text{Re}^{-3/4} \ell_0, u_v \sim \text{Re}^{-1/4} U_0$
- Magnetic resistive scale ℓ_η (Pm-dependent)
- Another important dimensionless quantity

- Eddy turnover time $\tau_{\text{NL}} \sim \ell_u/u$
- Flow/eddy correlation time τ_c

$$\text{St} = \frac{\tau_c}{\tau_{\text{NL}}} \quad \text{Strouhal/Kubo number}$$

The magnetic Prandtl number landscape

- Wide range of P_m in nature

- Liquid metals have $P_m \ll 1$
- Computers have $P_m \sim O(1)$

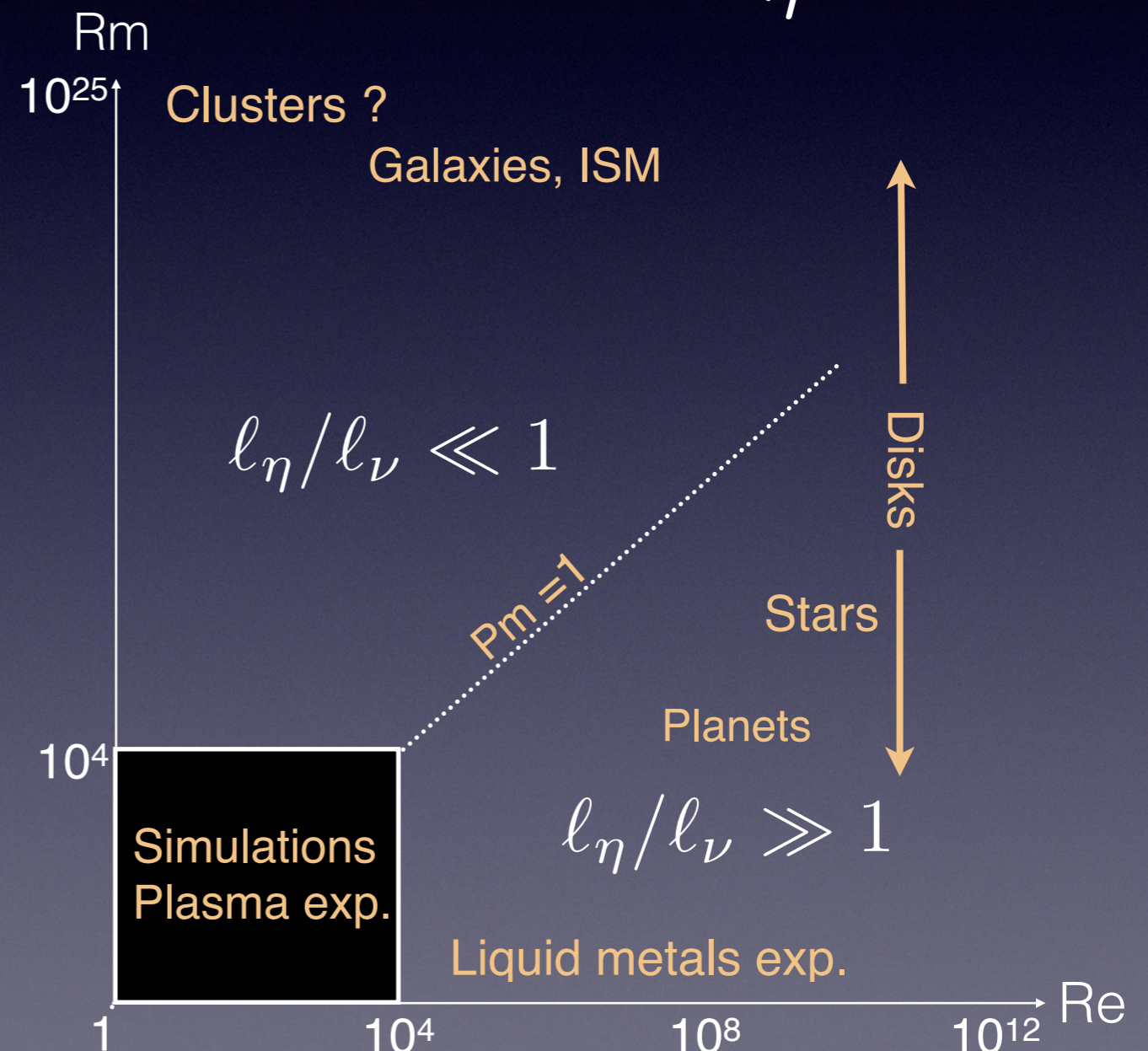
- For a collisional hydrogen plasma [Te=Ti in K, n in S.I.]

$$P_m = 2.5 \times 10^3 \frac{T^4}{n \ln \Lambda^2}$$

- $P_m < 1$ and $P_m > 1$ seemingly very different situations

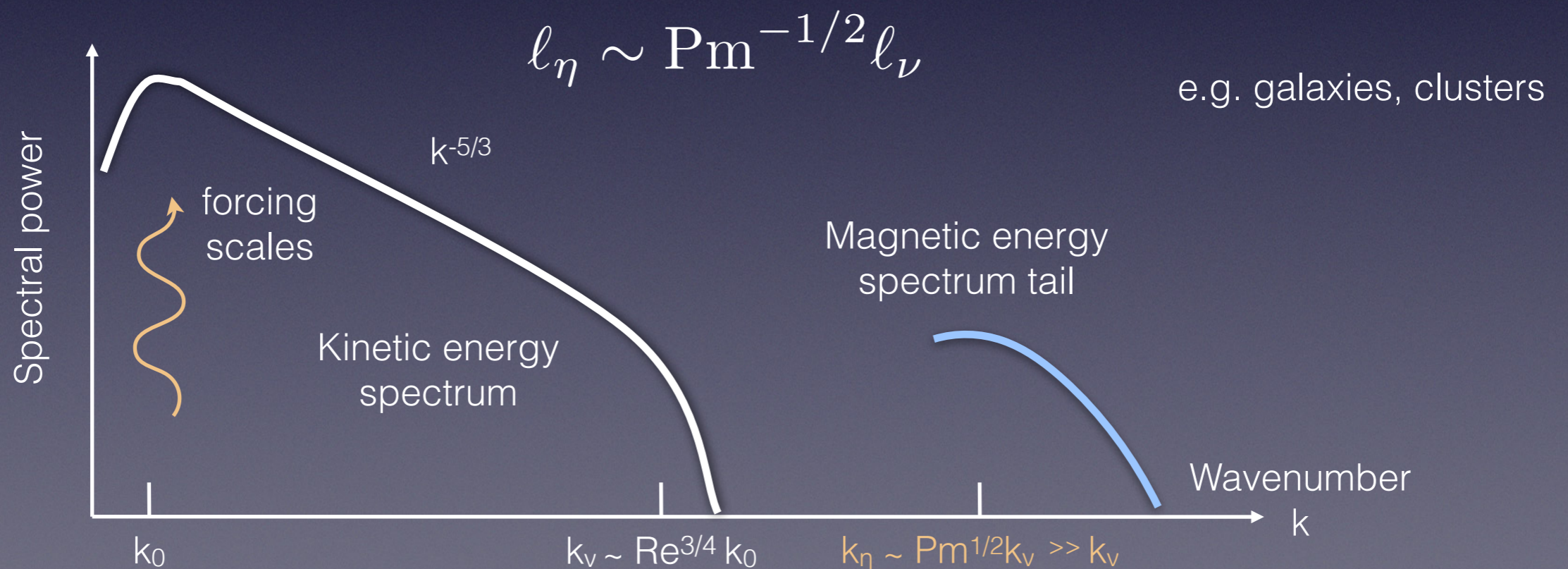
- Naively, $P_m > 1$ makes life easier for magnetic fields

$$P_m = \frac{\nu}{\eta}$$



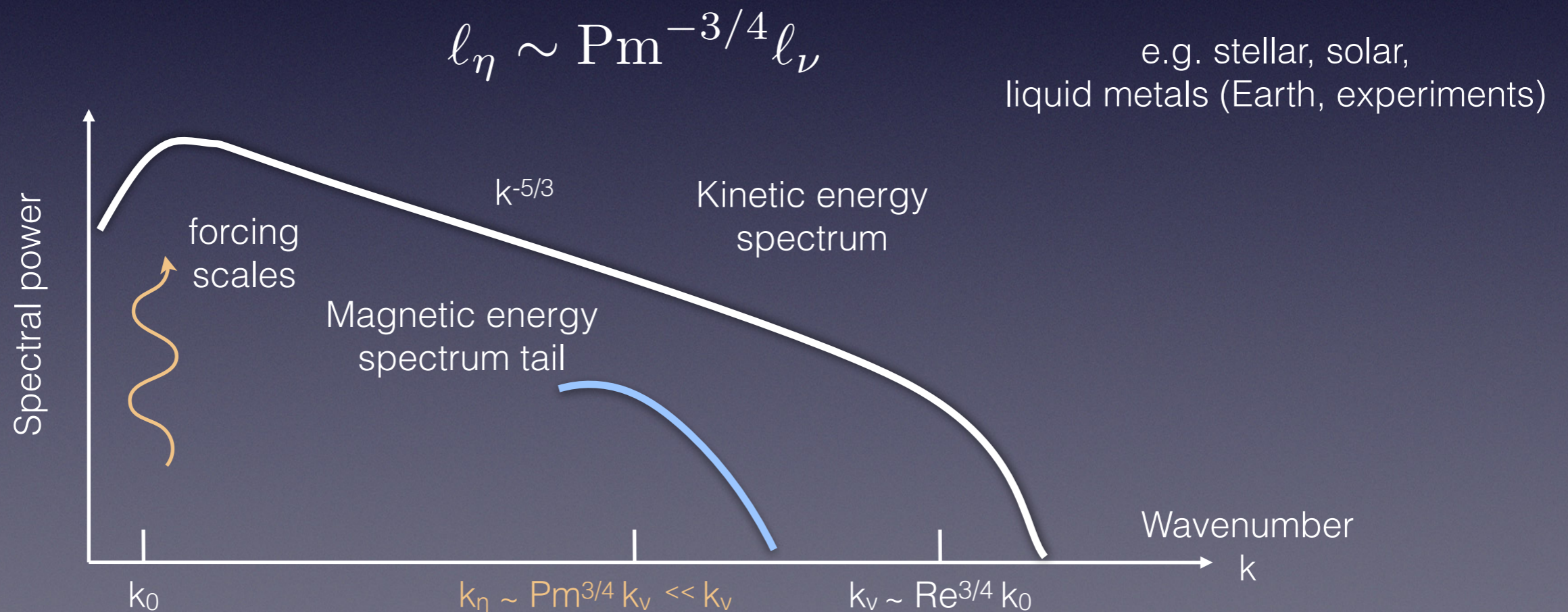
Large magnetic Prandtl numbers

- $Pm > 1$: resistive cut-off scale is smaller than viscous scale
 - In Kolmogorov turbulence, rate of strain goes as $\ell^{-2/3}$
 - Viscous eddies are the fastest at stretching B: $u_v / \ell_v \sim Re^{1/2} U_0 / \ell_0$
 - To estimate the resistive scale ℓ_η , balance stretching by these eddies $\sim u_v / \ell_v$ with ohmic diffusion rate η / ℓ_η^2



Low magnetic Prandtl numbers

- $Pm < 1$: resistive cut-off falls in the turbulent inertial range
 - To estimate the resistive scale ℓ_η , balance magnetic stretching by the eddies at the same scale $\sim u_\eta/\ell_\eta$, with diffusion η/ℓ_η^2
 - i.e., $Rm(\ell_\eta) = u(\ell_\eta) \ell_\eta / \eta \sim 1$



Dynamo fundamentals

- The problem of exciting a dynamo is an instability problem
 - Growth requires stretching to overcome diffusion (measured by $R_m = \frac{\ell_0 U_0}{\eta}$)
- Kinematic dynamo problem: $\frac{\partial \mathbf{B}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{B} = \mathbf{B} \cdot \nabla \mathbf{u} + \eta \Delta \mathbf{B}$
 - Find exponentially growing solutions of the linear induction equation (velocity field is prescribed)
- Dynamical problem considers effects of Lorentz force on \mathbf{u}
 - Saturated state of kinematic dynamos: non-linear magnetic back reaction
 - Subcritical scenarios: e.g. joint excitation of \mathbf{u} and \mathbf{B} via MHD instabilities
- Slow vs Fast
 - A dynamo is slow/fast if its growth rate does/doesn't vanish as $\eta \rightarrow 0$

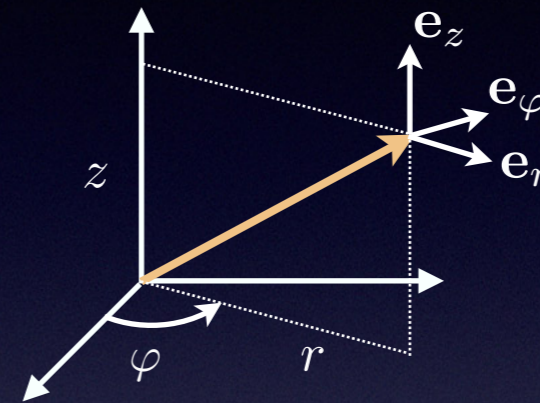
Cowling's antidynamo theorem

- Axisymmetric dynamo action is impossible [Cowling, MNRAS, 1933]

- In polar geometry, write

- $\mathbf{B} = \nabla \times (\overset{\text{Poloidal}}{\chi \mathbf{e}_\varphi / r}) + \overset{\text{Toroidal}}{r\psi \mathbf{e}_\varphi}$

- $\mathbf{u} = \mathbf{u}_{\text{pol}} + r\Omega \mathbf{e}_\varphi$



$$\frac{\partial \chi}{\partial t} + \mathbf{u}_{\text{pol}} \cdot \nabla \chi = \eta \left(\Delta - \frac{2}{r} \frac{\partial}{\partial r} \right) \chi \quad \text{No source term}$$

$$\frac{\partial \psi}{\partial t} + \mathbf{u}_{\text{pol}} \cdot \nabla \psi = \mathbf{B}_{\text{pol}} \cdot \nabla \Omega + \eta \left(\Delta + \frac{2}{r} \frac{\partial}{\partial r} \right) \psi$$

- Poloidal flow can only redistribute flux so χ must decay ultimately
- As χ decays, so must the toroidal field
- Note: only applies if \mathbf{u} and \mathbf{B} share the same symmetry axis

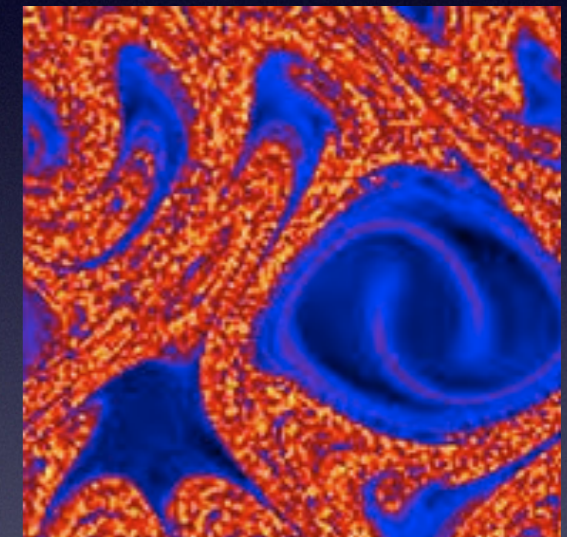
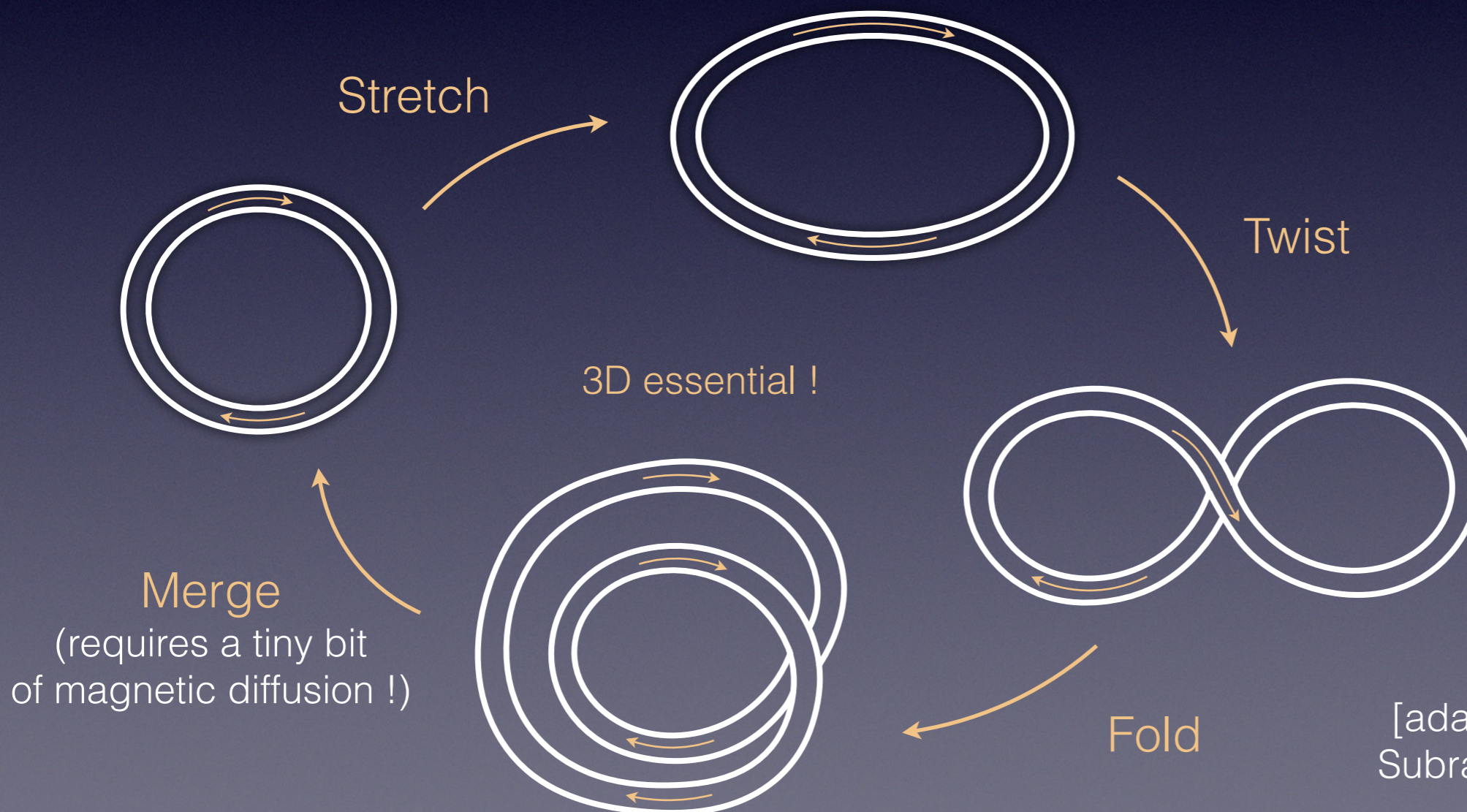
Antidynamo theorems and their implications

- Many other antidynamo results can be proven
 - Plane two-dimensional motions cannot sustain a dynamo [Zel'dovich's theorem, JETP 1957]
 - A purely toroidal flow cannot sustain a dynamo
 - $\mathbf{B}(x, y, t)$ cannot be a dynamo field
- Dynamos are only possible in “complex” geometries or flows
 - An extra burden for both theory and numerics
 - A popular “minimal” configuration is 2.5D (or 2D-3C)
 - $\mathbf{u}(x, y, t)$ with all three components non-vanishing
 - $\mathbf{B}(x, y, z, t) = \mathcal{R} \{ \mathbf{b}(x, y, t) e^{ik_z z} \}$

The fast dynamo paradigm

[Vainshtein & Zel'dovich, SPU, 1972]

- Chaotic stretching, twisting, folding and merging of field lines
 - For small diffusion, field doubles at each “iteration” (characteristic time)
 - Exponential growth with “ideal” growth rate $\gamma_\infty = \ln 2 \sim$ stretching rate



Lyapunov exponents of Galloway-Proctor flow [credits F. Cattaneo]

[adapted from Brandenburg & Subramanian, Phys. Rep. 2005]

An imperfect dichotomy

- Large-scale dynamo effect
 - Magnetic field generated on
 - long system time ($\Omega^{-1}, \mathcal{S}^{-1}$), spatial scales (L) much larger than flow scales ℓ_0
 - also lots of magnetic fluctuations on low and sub flow scales down to the magnetic resistive scale
- Small-scale dynamo effect
 - Magnetic field generated on short time (ℓ/u), spatial scales (ℓ) from flow scales down to the resistive scale
- Each of these can be excited by laminar or turbulent flows
- They have traditionally mostly been described by different theories
 - in all MHD astrophysical settings, large-scale dynamos are swamped by small-scale ones
 - this creates a lot of theoretical difficulties
- MHD instabilities also play a key role in large-scale dynamos
 - the magneto-rotational, and other magnetoshear instabilities
 - Kelvin-Helmholtz instability coupled to magnetic buoyancy